

Patent Claims

1. Method for recording and storing the optically detectable data of object on a storage medium, characterized in that a sequence of a plurality of individual recordings of the object are made with a camera at various spatial settings with respect to the relative position between the object and the camera; in that the sharply imaged areas of the individual recordings are determined; and in that the sharply imaged areas of all the individual recordings are assembled to form one or a plurality of resulting images.
2. Method as defined in Claim 1, characterized in that the individual recordings are stored in a computer; in that the sharply imaged areas of the individual recordings are determined by the computer with the aid of digital methods; and in that the resulting images are assembled with the aid of the computer.
3. Method as defined in Claim 2, characterized in that the sharply imaged areas are determined by digital formation of the derivative.
4. Method as defined in Claim 1, Claim ~~2~~, or Claim ~~3~~, characterized in that the parameters for recording the

SH
CN

~~individual r
in that th
this compu~~

THE

[illegible]

9. ^{claim 1}
~~Method as defined in one of the preceding claims,~~
characterized in that a CCD camera is used as the camera for
recording the sequence of individual recordings.

10. ^{claim 1}
~~Method as defined in one of the preceding claims,~~
characterized in that initially all the individual
recordings of the sequence are stored in the computer; and
in that the sharply imaged areas are identified after
recording of the sequence of individual recordings has been
concluded.

11. ^{claim 1}
~~Method as defined in one of preceding claims,~~ characterized
in that the sharply imaged areas of each individual
recording of the sequence are identified and incorporated
into the resulting image immediately after they have been
recorded.

12. ^{claim 1}
~~Method as defined in one of the preceding claims,~~
characterized in that a plurality of resulting images is
assembled from the sequence of individual recordings,
different areas of the object or different features of the
object being shown in the resulting images in each instance.

13. ^{sub} Method is defined in ^{claim 1} ~~one of the preceding Claims,~~

characterized in that the image plane is divided into a plurality of areas; and in that the areas are processed in parallel.

14. ^{sub} Method as defined in ^{claim 1} ~~one of preceding Claims,~~ characterized in that it is used to identify the features of a finger.

15. Method as defined in ^{claim 1} ~~one of preceding Claims,~~ characterized in that the object is illuminated with a light source.

16. Method as defined in Claim 5, characterized in that a pulsed light source that is synchronized with the camera is used.

17. ^{sub} Method as defined in Claim 15 ~~or 16,~~ characterized in that the object is illuminated by a plurality of light sources of different wavelength ranges and in different arrangements.

18. Method as defined in ^{claim 15} ~~one of the Claims 15 to 17,~~ characterized in that the object is illuminated as long as it is moving towards the camera and away from the camera.

